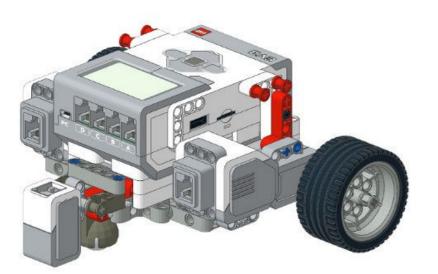


Modular Design



A POSTERIORI Play · Experience · Learn

Why Use a Modular Design?

- Large number of missions
- Different mechanism for each mission
- Quick changing of parts
 - Only have 2.5mins
 - Barely have enough time to complete all missions



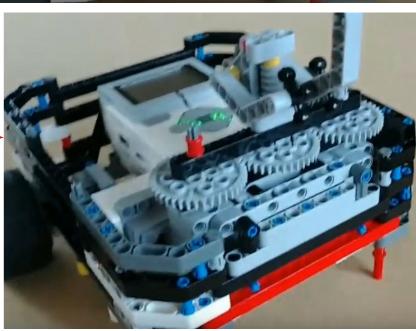
Techniques for Attachments

- Blue Axle Pins
- Slots in and out easily
- Not very strong



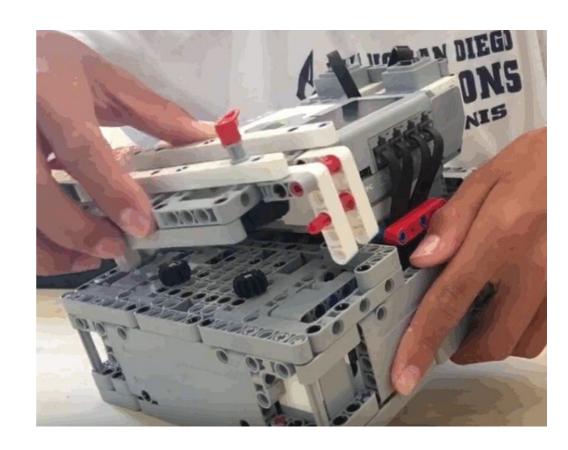


with attachment mounted



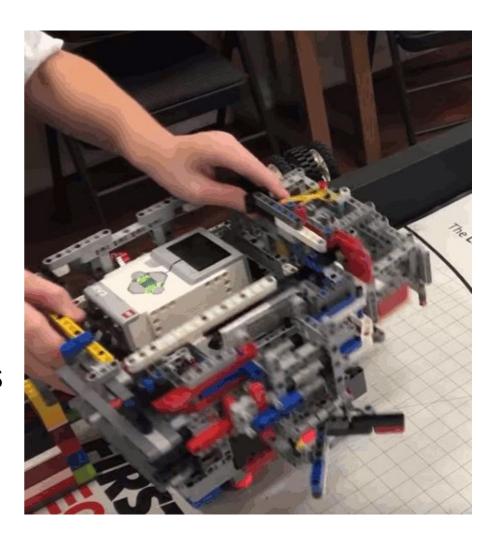
Techniques for Attachments

- Built slots
- More parts
- Stronger and more stable



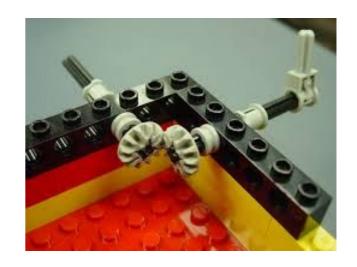
Techniques for Attachments

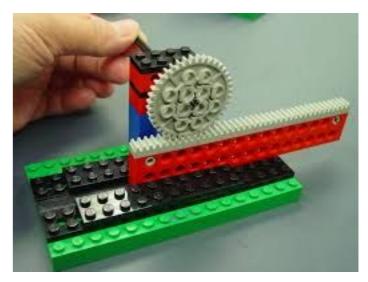
- Build a "Box"
 - Stable and fast
 - Can attach mechanisms on all sides
 - Use a lot of space and parts
- Use normal pins
 - Takes a few more seconds to attach and remove



Transmitting Power

- Mechanism often needs to be powered
- Besides just transmitting power:
 - Direction of rotation may need to be changed
 - May need to change from rotary to linear motion
 - Uses gears





Transmitting Power

- Directly plug into motor
 - Axles may get stuck in motor
 - Attachment responsible for gears (if required)

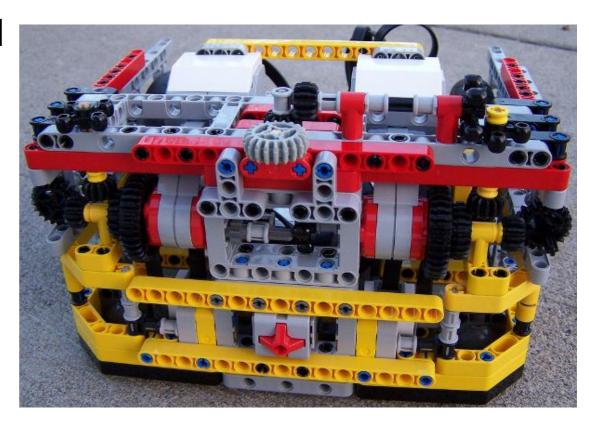


- Use gears
 - Easier on and off
 - Increased backlash



Transmitting Power

- Multiple outputs
 - Each motor connected to multiple output gears in different directions
 - Less gears required on attachments



Tips

- Think ahead:
 - Work on one mission at a time...
 - but plan for all of them in advance
- Don't fall prey to this...
 - Work on mission 1... Success!
 - Work on mission 2... Need to change robot
 - Succeed on mission 2!
 - Now the robot don't work on mission 1 due to the changes...

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